

# Multidimensional scaling has benign landscape under mild rank relaxation

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with

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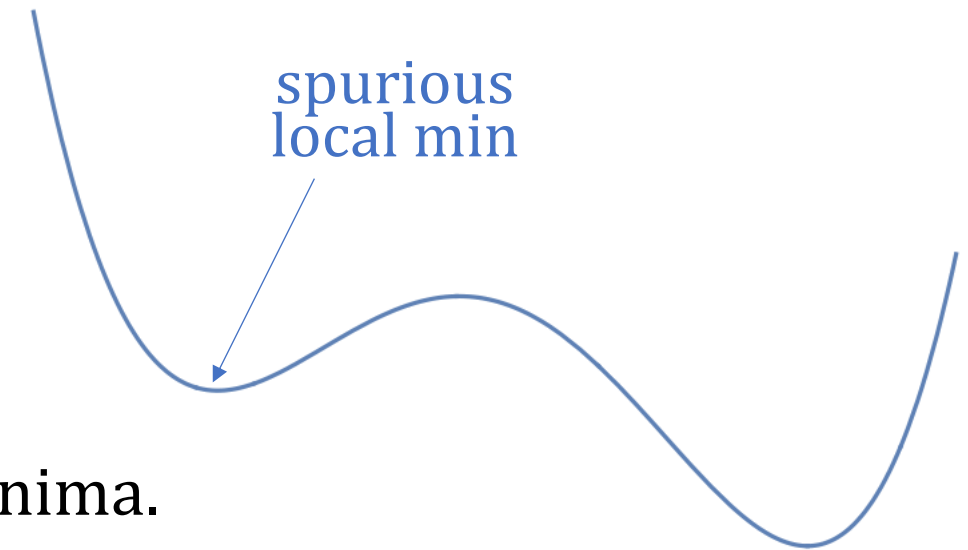
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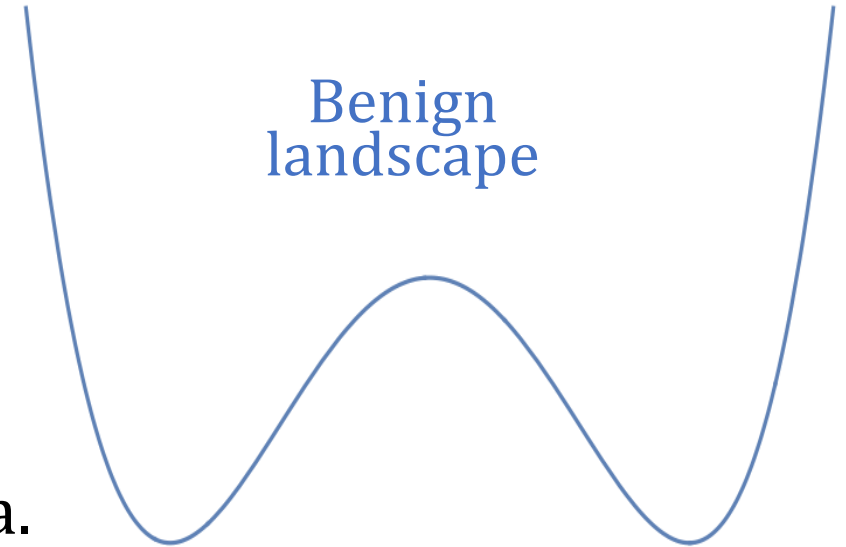
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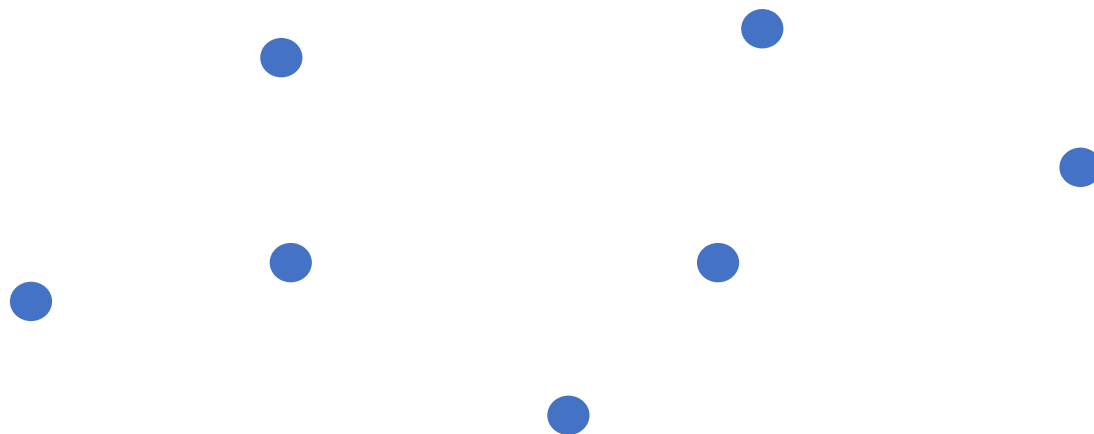
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# The problem

$n$  unknown points  $z_1^*, z_2^*, \dots, z_n^*$  in  $\mathbb{R}^\ell$ .

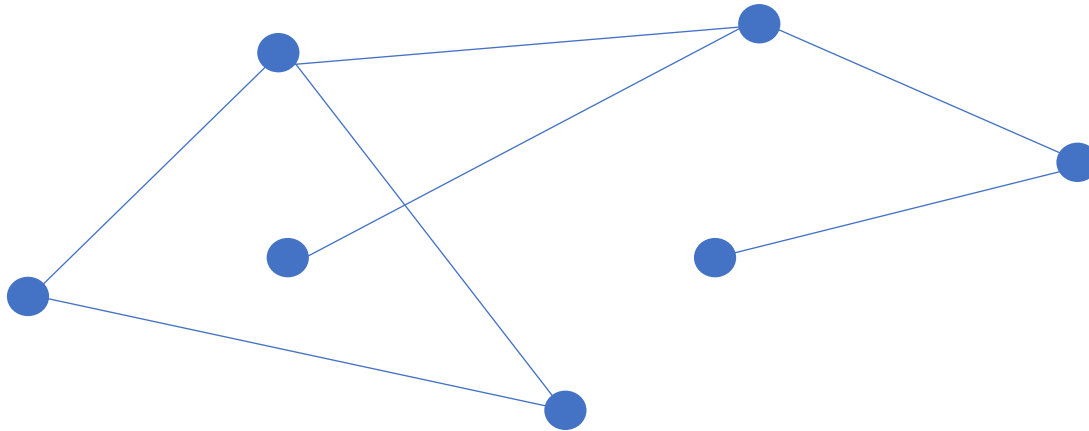


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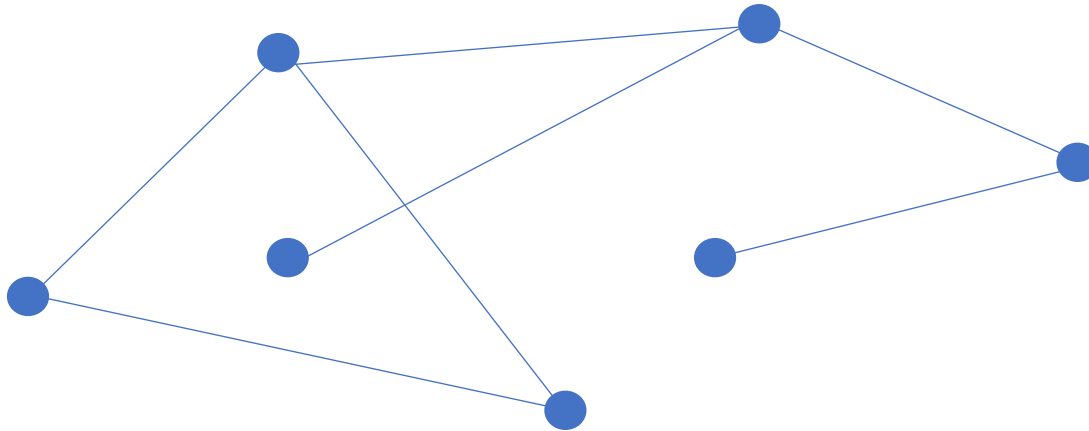
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**Goal:** recover the  $n$  points (up to translation & rotation)



# Applications

Robotics (**sensor network localization**),  $\ell = 2,3$

Data analysis (metric **multidimensional scaling**)

Graph theory (rigidity)

# Optimization problem

$$\min \sum_{ij \in E} \left( \|z_i - z_j\|^2 - d_{ij}^2 \right)^2, \quad d_{ij} = \|z_i^* - z_j^*\|$$

over  $z_1, z_2, \dots, z_n \in \mathbb{R}^\ell$

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Possible variations: Noisy measurements, landmarks, ...

Our focus: (nearly) complete graphs, no noise

# Synthetic experiments

Recipe (all distances known):

- (1) Choose ground truths  $z_1^*, z_2^*, \dots, z_n^*$  at random (normal iid)
- (2) Run gradient descent/trust regions/etc.
- (3) Find global min?
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**Open Question:** Does s-stress have spurious local minima? Are all 2-critical points global minima?

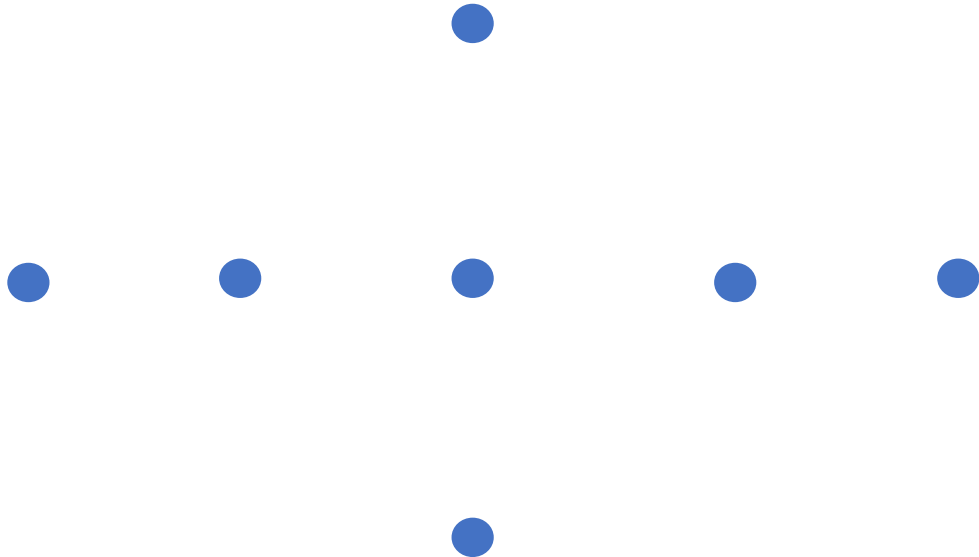
\* Malone & Trosset 2000, Parhizkar 2013, etc.



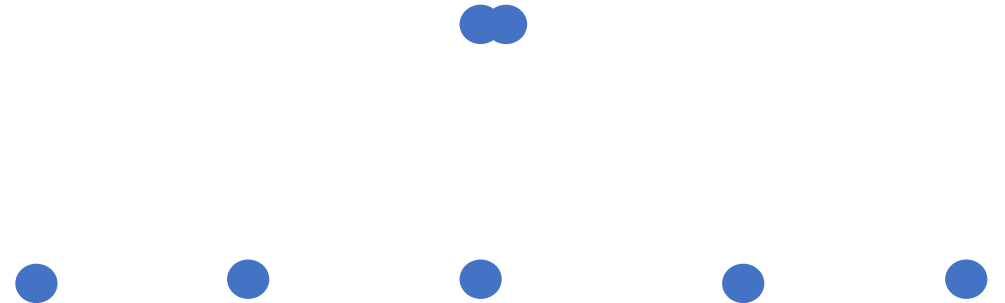
# Counterexamples

s-stress can have spurious strict local minima!

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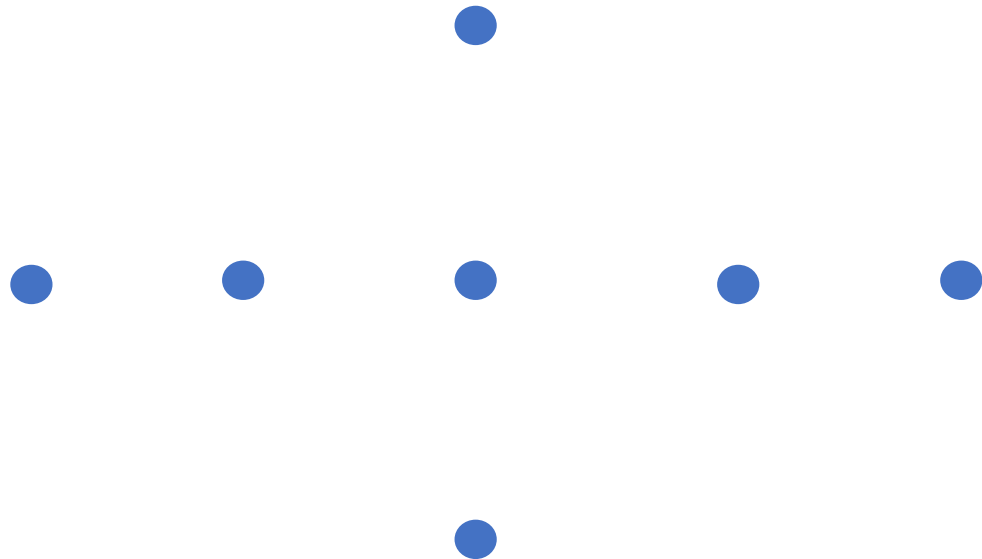
Spurious configuration  $z_1, z_1, \dots$



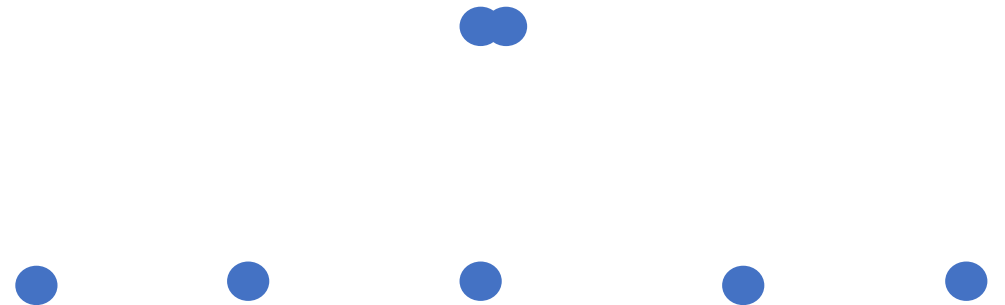
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Spurious configuration  $z_1, z_2, \dots$



Set of ground truths with spurious local minima has positive measure

# Nonconvex relaxation

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If  $k = n - 1$ , landscape is benign (later)

**Can we do better?**

# Results

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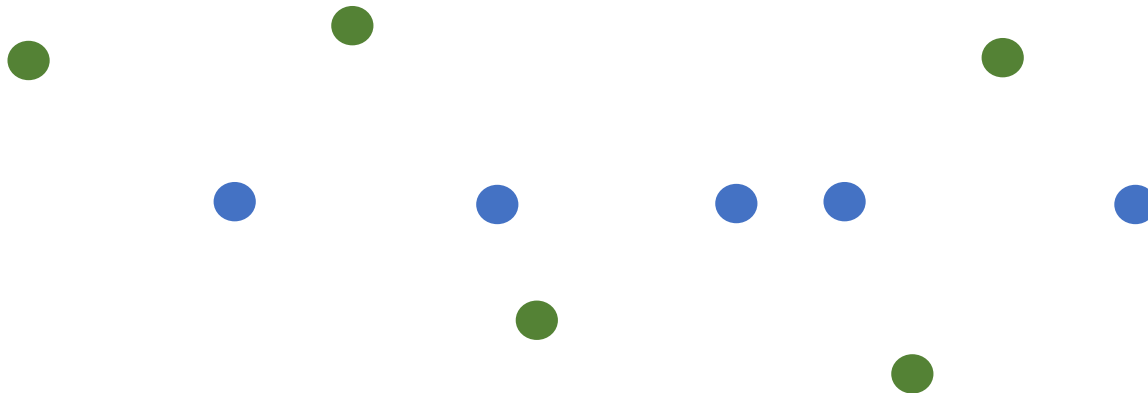
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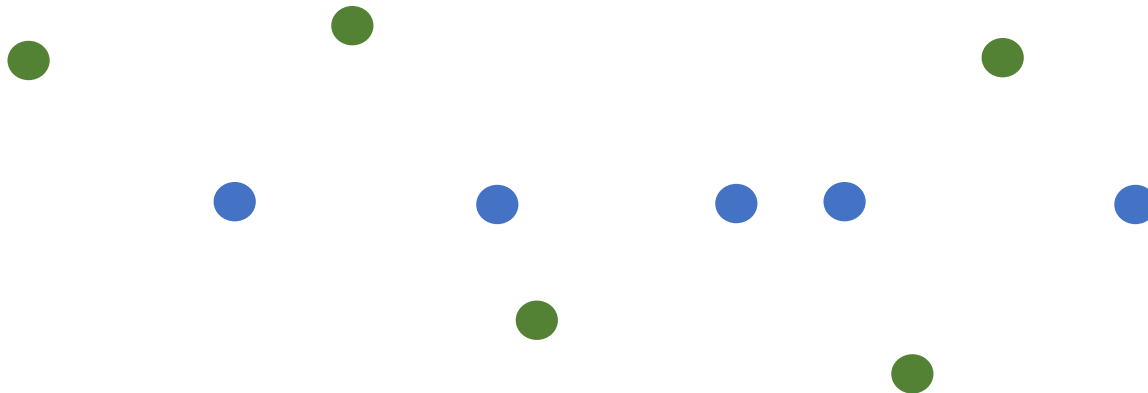


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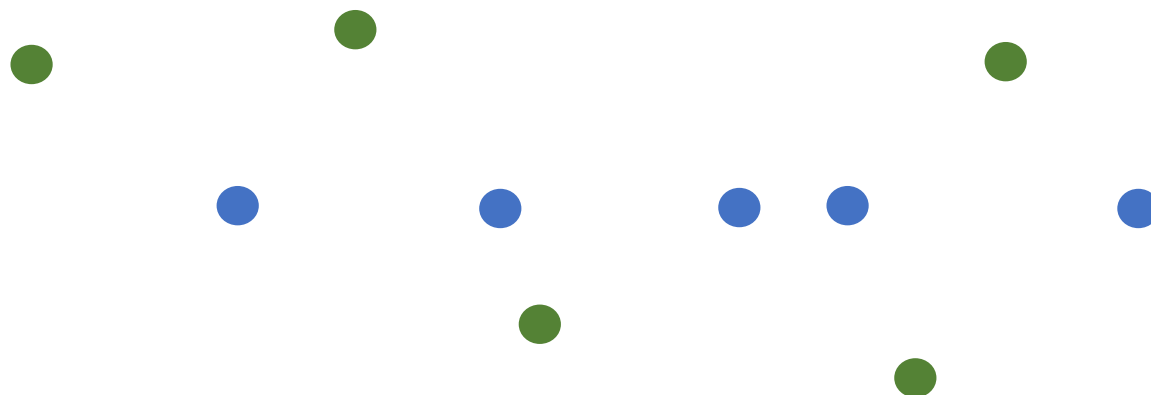
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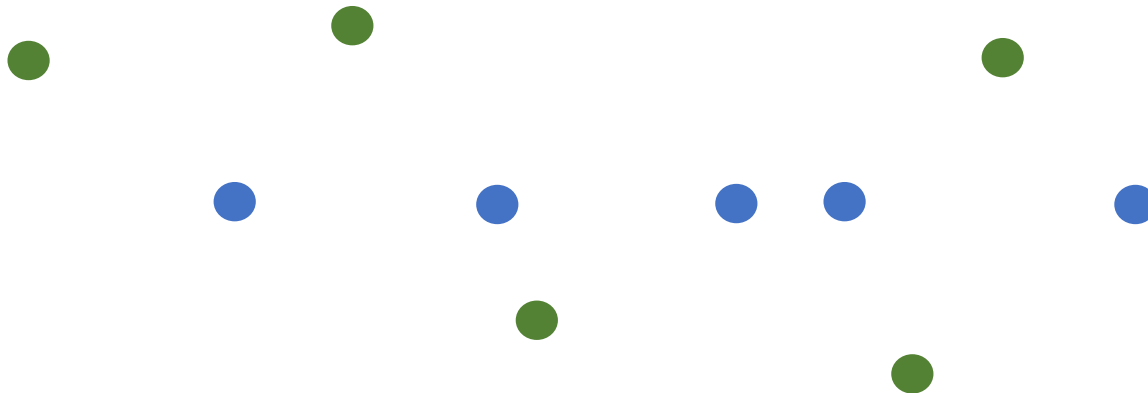


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**Goal:** **perturb** 1-critical configuration to decrease cost

Best linear transformation  $z_i \mapsto Rz_i$  mapping **1-critical config** to **ground truth**

$$R = \operatorname{argmin}_R \|Z_* - ZR^\top\|^2, \quad Z = \begin{pmatrix} z_1^\top \\ \vdots \\ z_n^\top \end{pmatrix} \in \mathbb{R}^{n \times k}$$

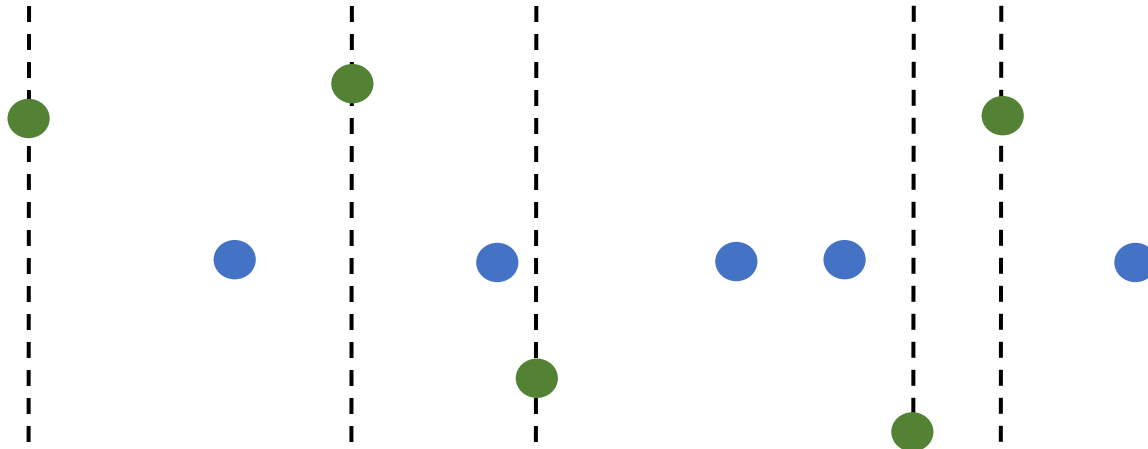


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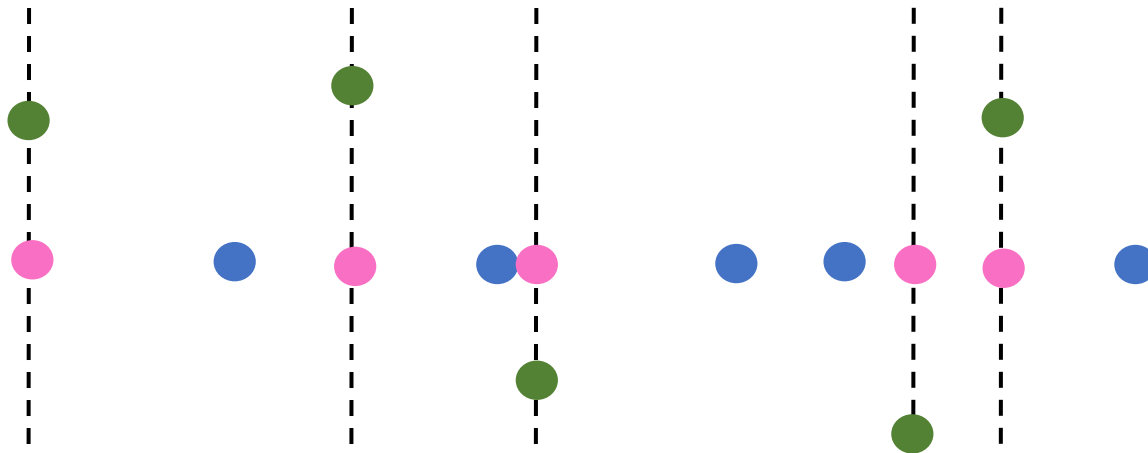


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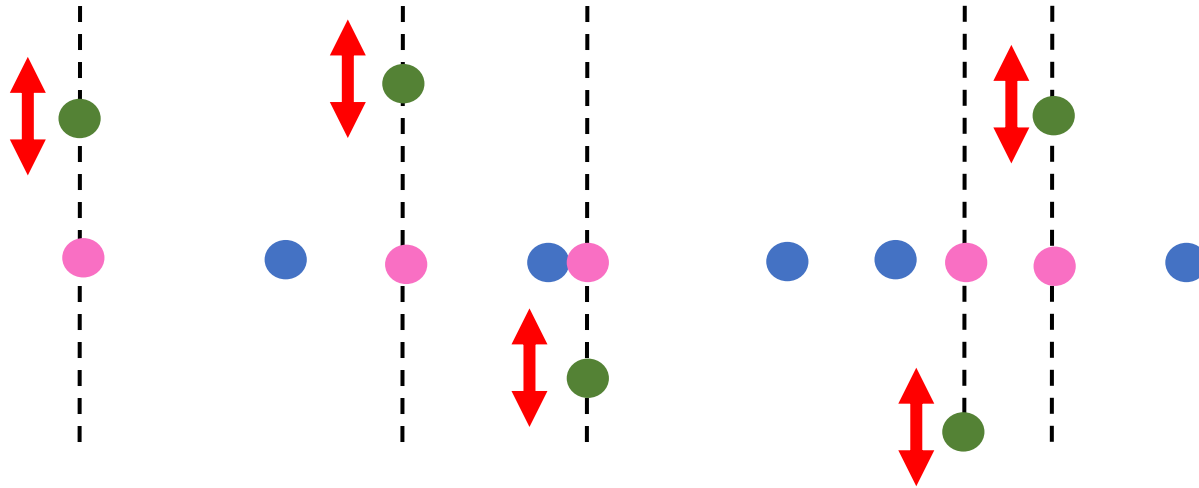
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The diagram illustrates the concept of a 1-critical configuration and its perturbation. It shows several vertical dashed lines. On each line, there are points of different colors: blue, pink, and green. Red double-headed arrows indicate perturbations of the green points. The points are arranged in a way that suggests a mapping from a 1-critical configuration to a ground truth configuration.

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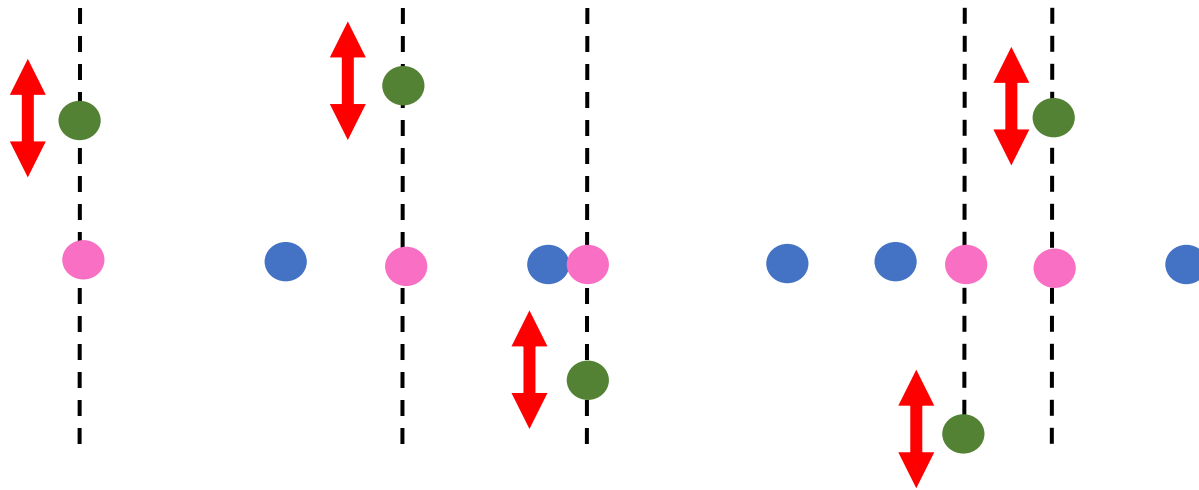
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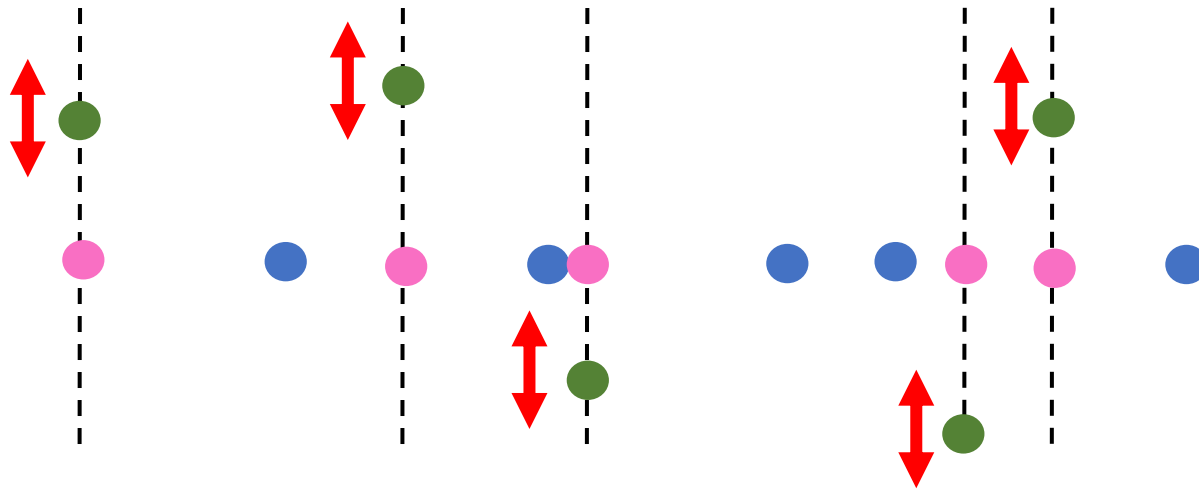


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For **isotropic GT**,  $k \approx \ell \log(n)$ , similar descent direction

**Randomize** over descent directions (instead of eigenvalue interlacing)



# Connection to low-rank optimization

# Notation and reformulation

$$Z = \begin{pmatrix} z_1^\top \\ \vdots \\ z_n^\top \end{pmatrix} \in \mathbb{R}^{n \times \ell}, \quad Z_* = \begin{pmatrix} z_1^{*\top} \\ \vdots \\ z_n^{*\top} \end{pmatrix} \in \mathbb{R}^{n \times \ell}$$

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$$[\Delta(Y)]_{ij} := Y_{ii} + Y_{jj} - 2Y_{ij} = \|z_i - z_j\|^2$$

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Restricted Isometry Property? No!  $\Delta^* \circ \Delta$  has condition number  $n$

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**General theorem:** If  $\Gamma$  is completely positive, contractive, “behaves well w.r.t. rank-1 matrices”, and

$$\langle Y, \Theta(Y) \rangle \leq c \langle Y, \Gamma(Y) \rangle \quad \forall Y$$

then landscape is benign when relax to  $k \approx \ell + \sqrt{c\ell}$ .

# Open questions

**Conjecture [arbitrary GT]:** Relaxing to  $k = \ell + 1$  is enough.

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Incomplete graphs (random, expanders, ...)

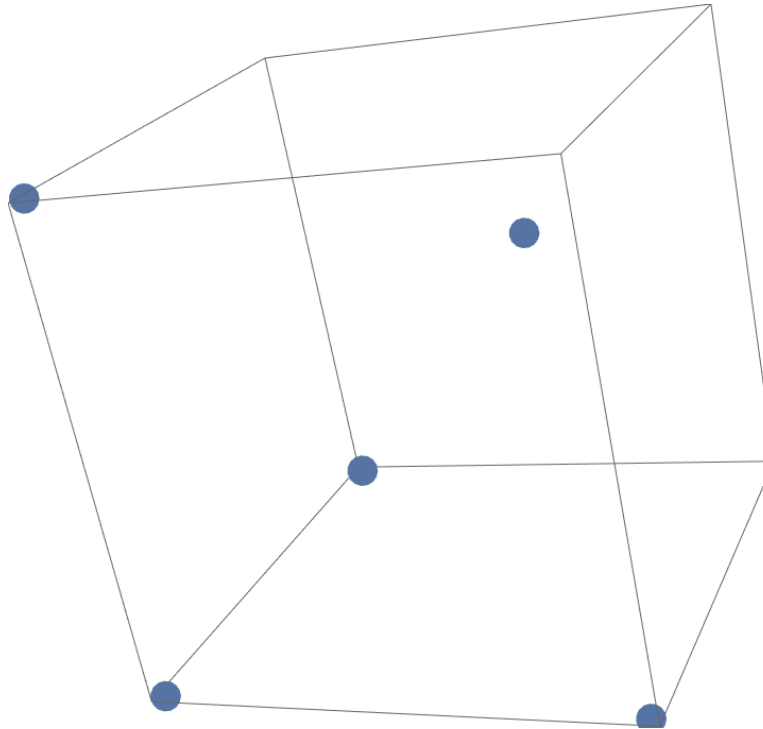
Many other SNL problems (noise models, trajectory localization, ...)

# Appendix

# Counterexamples

Minima number of points to have spurious local minima?

$$\ell + 2 \text{ (for } \ell \geq 5 \text{)}$$





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